

# Finite Element Method for FAD mechanics

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## Problem and objective

Problem

Objective

## Method

FEM

Equation of the mechanics

Newton Raphson method

Adaptation to FAD

## Data

Cable input

Environment input

## Examples

Fishing gear

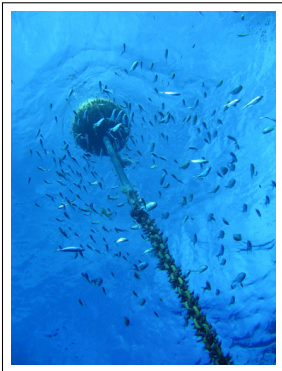
Fish cage

FAD behaviour

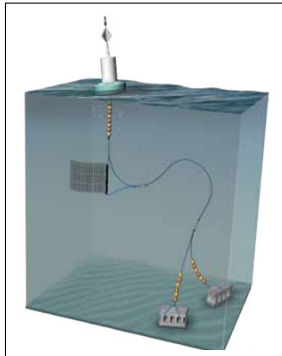
## Discussion

# Problem

Mechanical behaviour of complex flexible marine structures

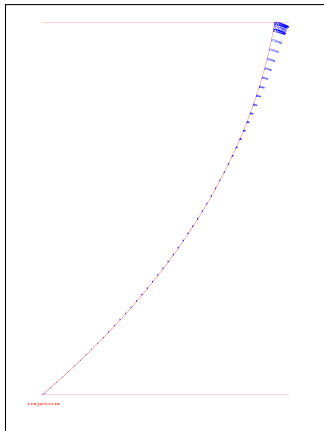


[www.peche.pf](http://www.peche.pf)

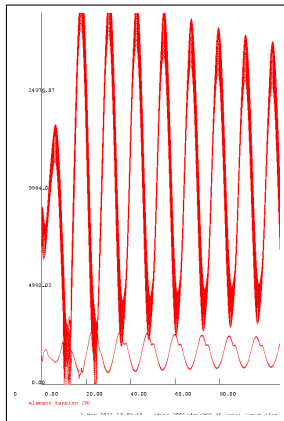


[www.pewenvironment.org](http://www.pewenvironment.org)

# Objective



Shape of the FAD,  
Displacement in wave.



Cable tension.

# Finite Element Method

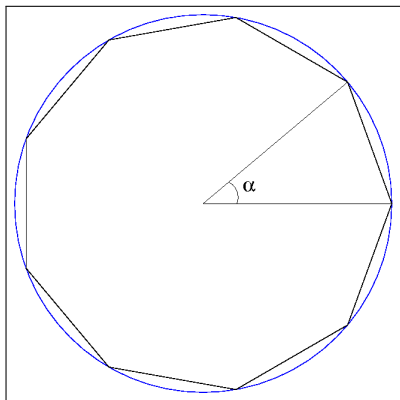
FEM modelling for complex structures  
used for the mechanical behaviour.

Principle:

- ▶ Split the structure in small elements,
- ▶ Approximation in these small elements,
- ▶ Re-build the structure.

## A simple example: Circle perimeter

- ▶ Perimeter is  $2\pi R$
- ▶ Perimeter split in  $n$  arc length
- ▶ Arc length approximated by cord length
- ▶ Cord length  $2R\sin(\frac{\alpha}{2})$
- ▶ Perimeter  $n$  times arc length

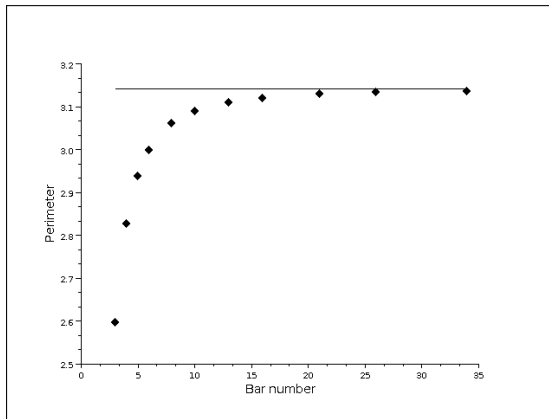


## Circle perimeter

$$R = 0.5$$

$$\text{Perimeter} = \pi$$

More of bars  
elements, better  
the accuracy.



Perimeter vs elements number

# Equation of the mechanics

- ▶ Equilibrium of forces leads to position
- ▶  $\mathbf{f} - \mathbf{m}\gamma = \mathbf{0}$
- ▶ nodes are extremities of elements
- ▶ Equilibrium :  $\mathbf{F}(\mathbf{X}) = \mathbf{0}$
- ▶ But  $\mathbf{F}(\mathbf{X}_{init}) \neq \mathbf{0}$

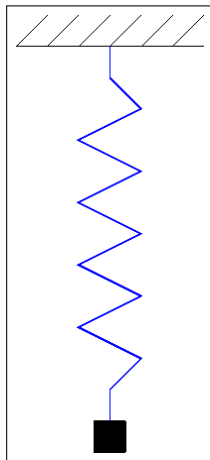


## Vector of position and force

- ▶ Vector of position  $\mathbf{X}$
- ▶ Vector of force  $\mathbf{F}$  depends on  $\mathbf{X}$
- ▶ How to find  $\mathbf{X}_{final}$  such that  $\mathbf{F}(\mathbf{X}_{final}) = 0$  ?

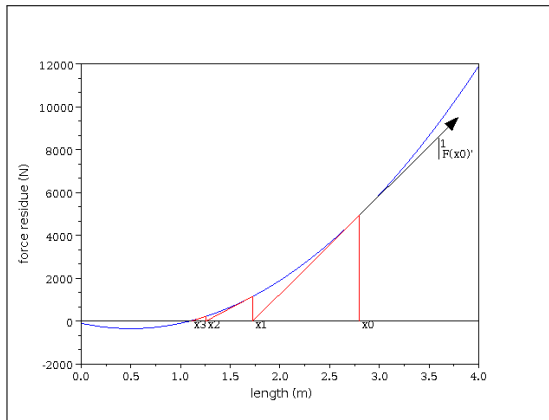
## Spring with 1DOF

- ▶  $F(x) = Ax \frac{x-l_0}{l_0} - Mg$
- ▶ Stiffness not constant
- ▶ What is the length ( $x$ ) at equilibrium?
- ▶ Equilibrium:  $F(x) = 0$



# Spring with 1DOF

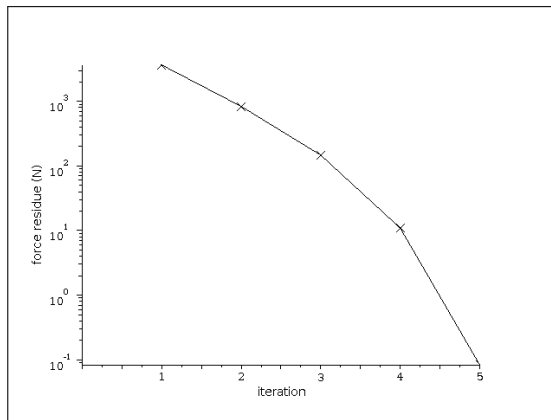
$$x_{k+1} = x_k + \frac{F(x_k)}{-F'(x_k)}$$
$$F'(x) = \lim_{h \rightarrow 0} \frac{F(x+h) - F(x)}{h}$$



Force residue vs length (X)

# Spring with 1DOF

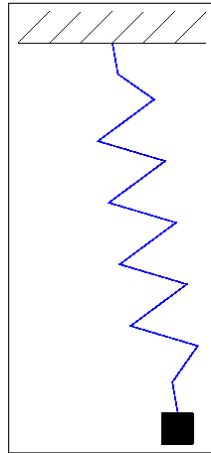
Convergence is quick



Force residue vs iterations

## Spring with 2DOF

- ▶  $F_x(\mathbf{X}) = T \frac{x}{l}$
- ▶  $F_y(\mathbf{X}) = T \frac{y}{l} - Mg$
- ▶  $T = A l \frac{l-l_0}{l_0}$  Stiffness not constant
- ▶  $l = \sqrt{x^2 + y^2}$



## Spring with 2DOF

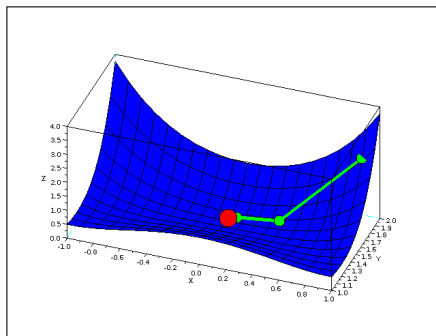
$$\mathbf{X}_k = \begin{cases} x_k \\ y_k \end{cases}$$

$$\mathbf{F}(\mathbf{X}_k) = \begin{cases} F_x(\mathbf{X}_k) \\ F_y(\mathbf{X}_k) \end{cases}$$

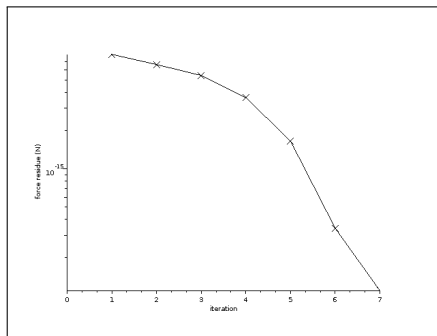
$$F'(\mathbf{X}_k) = \frac{A}{l_0 l_k} \begin{cases} l_k^2 - l_0 l_k + y_k^2 & x_k y_k \\ x_k y_k & l_k^2 - l_0 l_k + y_k^2 \end{cases}$$

$$\mathbf{X}_{k+1} = \mathbf{X}_k + \frac{\mathbf{F}(\mathbf{X}_k)}{-F'(\mathbf{X}_k)}$$

## Spring with 2DOF



Force norme



Force residue vs iterations

# Adaptation to FAD

Cables split in bar element

- ▶ Bar elastic
- ▶ Bar straight
- ▶ Length
- ▶ Diameter ...

Floats approximated by parallelepiped

- ▶ Mass
- ▶ Volume ...



# Forces on FAD

Forces **F** depend on node position **X**

- ▶ Tension
- ▶ Weight
- ▶ Floatability
- ▶ Drag
- ▶ Dynamic
- ▶ Bottom contact

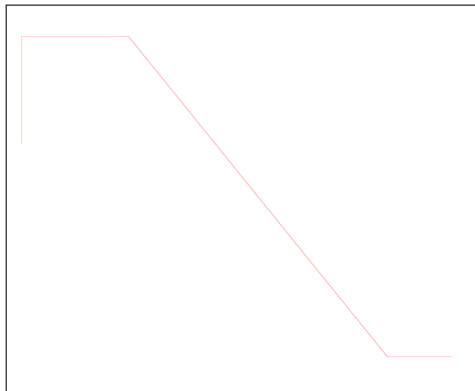
- ▶  $T_e = \frac{l-l_0}{l_0} AE$
- ▶  $W_e = Mg$
- ▶  $F_l = V\rho g$
- ▶  $D_r = \frac{1}{2}\rho CdSV^2$
- ▶  $I_n = -M\gamma$
- ▶  $B_o = (Z_b - Z)K_b$

$$\mathbf{F} = T_e + W_e + F_l + D_r + I_n + B_o$$

# Cable input

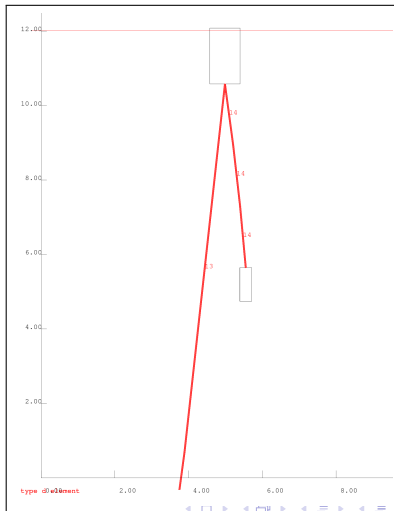
```

number of cables      :14
cable                 :1
extremities no x y z type :
1 0 0 -1500 1
2 20 0 -1500 2
traction stiffness (N) :3923000
compression stiffness (N) :0
length (m)           :20
density (kg/m3)      :1050
diameter (m)         :0.044
cd                   :1.2
f                    :0.08
element number       :3
node type            :2
    
```



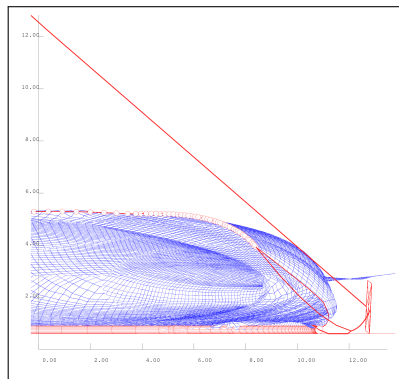
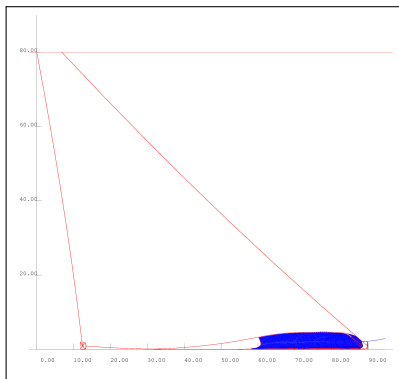
# Environment input

```
current direction (deg) :45  
current amplitude (m/s) :1.0  
  
wave period (s) :12.0  
wave height (m) :20.0  
wave direction (deg) :0
```



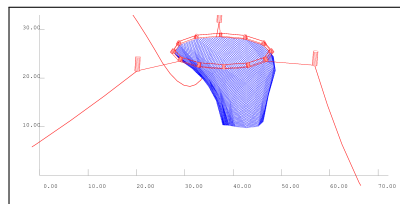
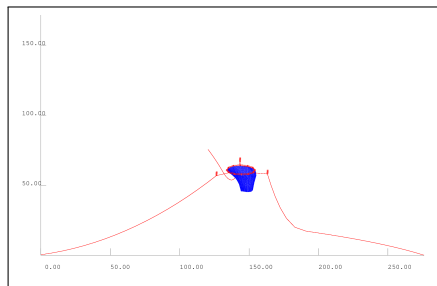
# Trawl

Bottom trawl:  
Netting, cables, floats, doors.



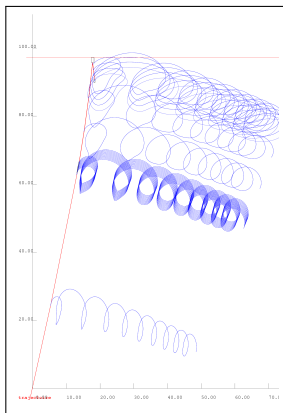
## Fish cage

Circular cage moored with 3 chains:  
Netting, cables, floats, chains.

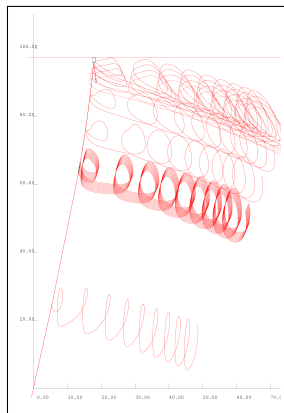


# FAD behaviour

## Mechanical behaviour of the FAD in waves



Displacement



Immersion

# Discussion

- ▶ Few current levels vs one level
- ▶ Large wave spectra vs Airy wave
- ▶ Accuracy: bar length (1m, 10m)
- ▶ Accuracy: time step (0.01s, 0.1s)
- ▶ Drag coefficient (1.2, 1.8) : flume tank tests
- ▶ Complex structures (plastic sheets) : flume tank tests
- ▶ Cable flexion

Thank you for your  
attention

